

Math 54 worksheet, September 14, 2009

1. Let T be the linear transformation from \mathbb{R}^3 to \mathbb{R}^3 which consists of first rotating 30 degrees about the z axis and then rotating 90 degrees about the x axis. (I haven't specified the directions of the rotations. Use whichever ones you prefer.) What is the matrix for T ? Can you describe T as a single rotation?

2. Let

$$A = \begin{bmatrix} -1 & 2 & 3 & 0 \\ 2 & -5 & 7 & 4 \\ 1 & -3 & 10 & 4 \end{bmatrix}$$

Find

- A basis for $\text{Col}(A)$
- A Schubert basis for $\text{Row}(A)$
- A reverse Schubert basis for $\text{Null}(A)$
- The dimension of $\text{LeftNull}(A)$ (Hint: you can figure this out just from the echelon form of A . You don't need to row reduce A^T)

Write the second row of A as a linear combination of the Schubert basis for $\text{Row}(A)$.

3. Let A be the same as in the previous question. Is the vector

$$\begin{bmatrix} 7 \\ 2 \\ 1 \\ 1 \end{bmatrix}$$

in $\text{Null}(A)$? Is the vector $[1 \ 2 \ 1 \ 1]$ in $\text{Row}(A)$? Is the vector space spanned by $[2 \ -4 \ -6 \ 0]$ and $[-1 \ 3 \ -10 \ -4]$ contained in $\text{Row}(A)$?

4. Let

$$B = \begin{bmatrix} -1 & 2 & -4 \\ 3 & -6 & 12 \\ 2 & -4 & 8 \end{bmatrix}$$

Find a reverse Schubert basis for $\text{LeftNull}(B)$.

5. Let S be the linear transformation from \mathbb{R}^3 to \mathbb{R}^3 which takes a vector and rotates it by 60 degrees around the axis spanned by $(1, 1, 0)$. Can you find a matrix for S ?



Hermann Schubert (1848-1911)