

1 *Define eigenspace (2.5 points).*

For a matrix  $A$  and  $\lambda$  an eigenvalue of  $A$ , the  $\lambda$ -*eigenspace* is the set of all vectors  $x$  such that  $Ax = \lambda x$ .

2 *Define what it means for a matrix to be diagonalizable (2.5 points).*

A matrix  $A$  is *diagonalizable* if and only if there exists a diagonal matrix  $D$  and an invertible matrix  $P$  such that  $A = PDP^{-1}$ .

3 *Define what it means for a quadratic form to be indefinite (2.5 points).*

A quadratic form  $Q(x)$  is *indefinite* if it assumes both positive and negative values, i.e.  $Q(x) < 0$  for some value of  $x$  and  $Q(x) > 0$  for some other value of  $x$ .

4 *Define orthogonal projection onto a subspace (2.5 points).*

If  $L$  is a linear subspace of  $\mathbb{R}^n$  and  $x$  a vector in  $\mathbb{R}^n$ , then the orthogonal projection of  $x$  onto  $L$  is the vector  $v$  such that  $\|x - v\|$  is minimized. Equivalently, it is the vector  $v$  such that  $x - v$  is orthogonal to every vector in  $L$ .