

1 Here is a matrix and its echelon form:

$$A = \begin{bmatrix} 1 & -2 & 9 & 5 & 4 \\ 1 & -1 & 6 & 5 & -3 \\ -2 & 0 & -6 & 1 & -2 \\ 4 & 1 & 9 & 1 & -9 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 9 & 5 & 4 \\ 0 & 1 & -3 & 0 & -7 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Find bases for  $\text{Col}(A)$  and  $\text{Nul}(A)$  and state the dimensions of these subspaces. (6 points)

A basis for  $\text{Col}(A)$  is those columns which have pivots in the echelon form of  $A$ , which are the first, second and fourth columns:

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ -2 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 5 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Since there are 3 vectors in the basis, the subspace is 3-dimensional.

The dimension of  $\text{Nul}(A)$  is 2, because that is the number of free variables, but to find a basis for  $\text{Nul}(A)$ , we need to find the reduced echelon form:

$$\begin{bmatrix} 1 & -2 & 9 & 5 & 4 \\ 0 & 1 & -3 & 0 & -7 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 9 & 0 & 14 \\ 0 & 1 & -3 & 0 & -7 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 & 0 & 0 \\ 0 & 1 & -3 & 0 & -7 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

From this, we read off the basis for  $\text{Nul}(A)$ :

$$\left\{ \begin{bmatrix} 0 \\ 7 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 3 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

(This is a reverse Schubert basis, but the problem did not ask about that.)

2 Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear transformation which takes a point, rotates it counter-clockwise 45 degrees, and then reflects it across the  $x_1$ -axis. Find a matrix for  $T$ . (4 points)

The matrix for a counter-clockwise rotation by  $\theta$  degrees is:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

The matrix for  $T$  is the product of the matrix for the reflection times the matrix for the rotation:

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$